CPE Mission Autonomy Overview

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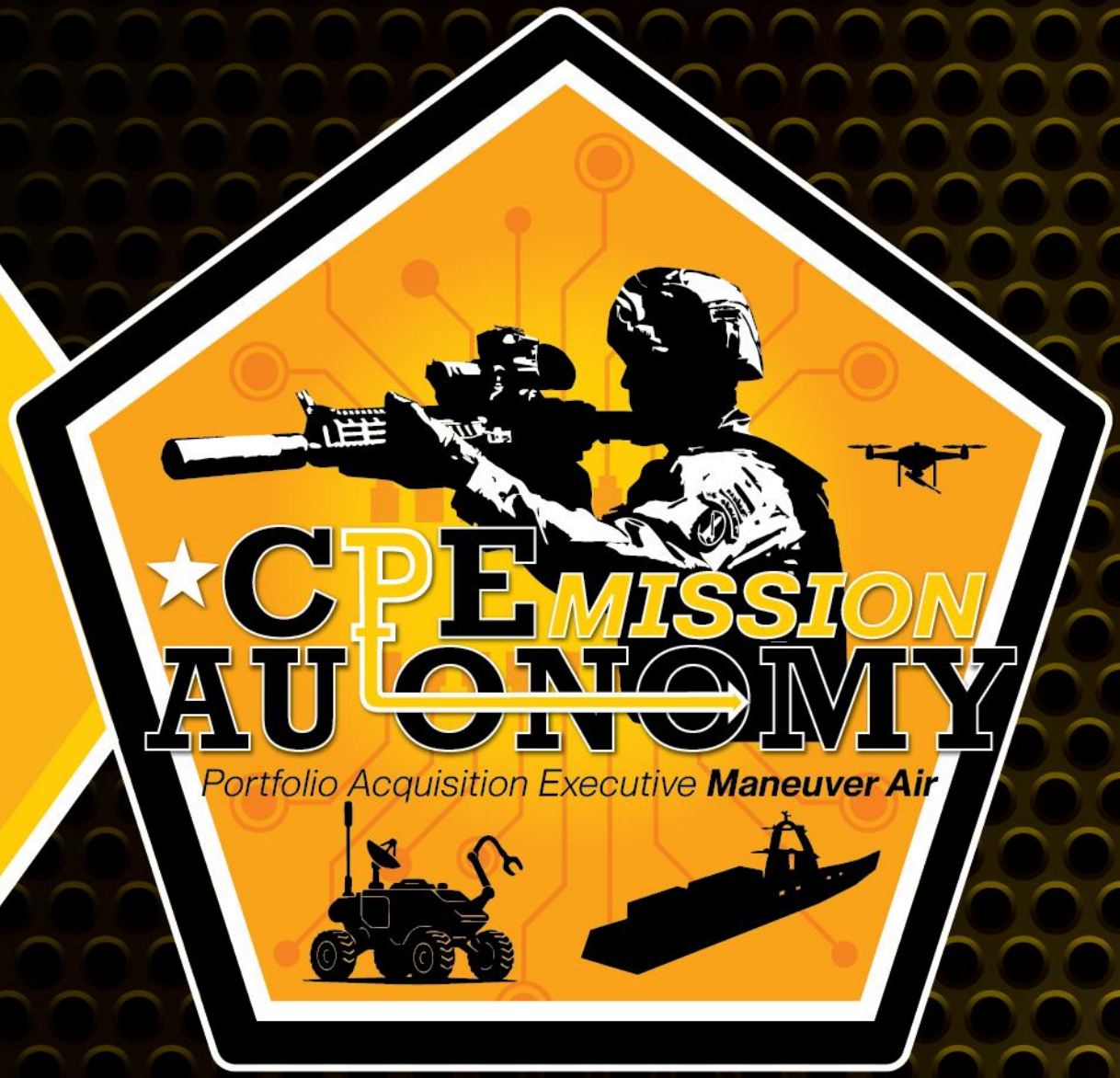


U.S. ARMY

BUILDING CPE MISSION AUTONOMY

Mission Statement

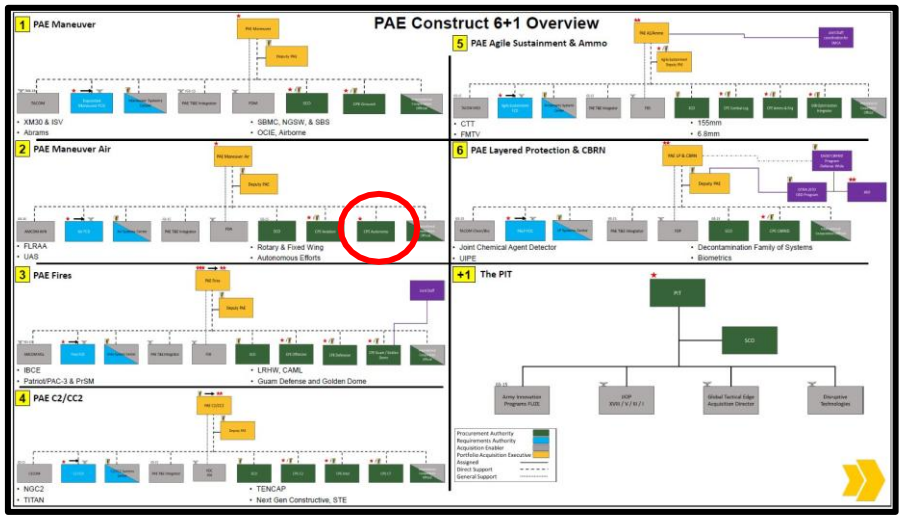
Increase Soldier situational awareness, lethality, and survivability by delivering interconnected unmanned system capabilities that accomplish missions autonomously and intuitively.

Vision

Empower Soldiers with the full force and scale of American innovation.

CPE Mission Autonomy – FIRST Principles

1. Deliver Formation-Based Mission Autonomy Capability to MBCTs, ABCTs, and SBCTs as the Top Priority
   - System of Systems Approach
   - Accelerate Robotic Control Architecture
   - CI/CD Approach for Autonomy Development
   - Identify and address key challenges (power, spectrum, bandwidth, cyber, EW, etc.)
   - Address all elements of DOTmLPF-P during prototyping
2. The Soldier Experience is Paramount
   - Intuitive
   - Robust/Reliable
   - Trainable
3. Close Partnership with PIT
   - Inform and support unit innovation cells
   - Focus development on relevant use cases
   - Prototype and iterate with TiC and Deliberate Transformation formations
4. Develop Sustainable Business Model
   - Adopt available industry solutions, Adapt/Modify when we can, Develop if we must
   - Utilize set-based design & selective MOSA approach to maximize competition & industry innovation
   - Affordable for the Army
   - Profitable for industry
   - Foster a healthy and robust industrial base with ability to scale

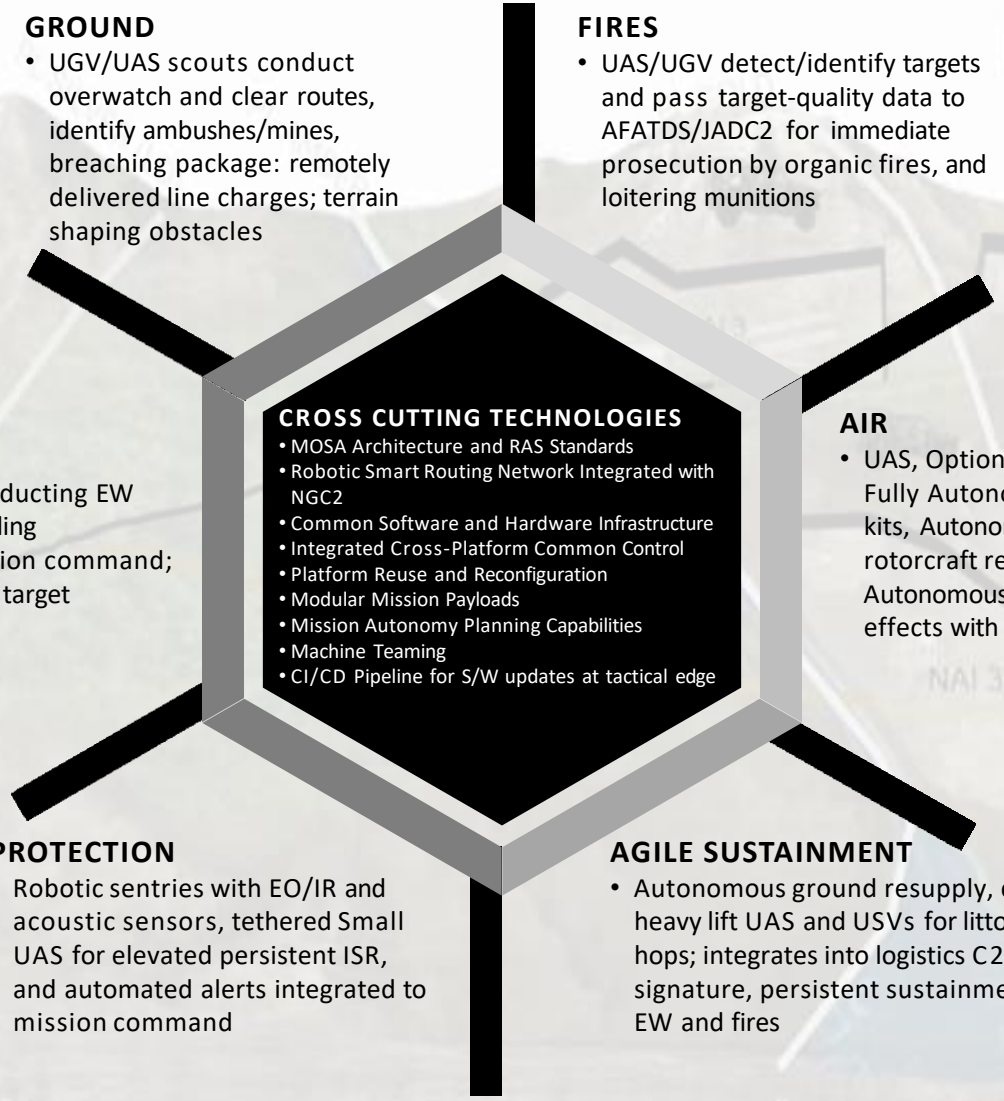


CROSS-CUTTING TECHNOLOGY AND ARCHITECTURE

U.S. ARMY

CPE MISSION AUTONOMY
Portfolio Acquisition Executive Maneuver Air

CPE Mission Autonomy plays a pivotal role in integrating cross-cutting robotic and autonomous system capabilities across the Army's warfighting functions by emphasizing MOSA architecture, commonality in software, hardware, common control and routing networks, as well as the reuse and reconfiguration of platforms and modular payloads.



Cross PAE coordination to ensure alignment across war fighting functions. The alignment of robotic and autonomous system solutions with specific use cases across PAE portfolios underscores the strategic importance of this cross-cutting initiative.

U.S. ARMY

CPE Mission Autonomy
BG Anthony Gibbs

Ft. Belvoir, VA

DCPE Mission Autonomy
Gary Keller

Ft. Belvoir, VA

CTO
Mike Rose

Warren, MI

Enable

SMEs, Tools, Plans
Industry gateway

PM Formation Based Mission Autonomy
(TBD – O6 CSL)

Fort Belvoir, VA

Mission Teams

Responsible for:
Formation Need/Use Case Definition
And Prioritization
Formation Experimentation (TIC→CTC)
Operational Evaluation
Tech Scouting

PdM Mission Autonomy All Arms Maneuver
O5 – CSL
LTC Brady Juelson

Mission Team: Reconnaissance, Screening, Breaching, TSO Emplacement
(1CD Alignment)

PdM Mission Autonomy Fires, C2&Counter-C2
O5 – CSL
LTC Graham Mullins

Mission Team: Target Identification, Automated Call-for-Fire, UAS-LM Hunter-Killer Ops, Range Extension, Electronic Warfare
(4ID Alignment)

PdM Mission Autonomy Agile Sustainment & Protection
O5 – CSL
LTC Jonathan Judy

Mission Team: Resupply, CASEVAC, Surveillance, Fixed Site Protection
(25ID Alignment)

Warren, MI

PM Autonomous Robotic Capabilities
COL Ken Bernier

Buy Items

Platforms and payloads

Ft. Belvoir, VA; APG, MD

PM Robotic Control and Integration
O6 – CSL
Rob Monto

Integrate & Deploy Systems

SoS Integration & delivery
CI/CD

Platforms, Payloads (w/Autonomy)

Unified C2 Architecture (Collaborative Autonomy)

Deliver

System of Systems
Integrated Formations